ON A MULTI-SERVER QUEUING SYSTEM WITH CONSTANT HOLDING TIME AND PRIORITIES Sixth

Manfred Langenbach-Belz

Technical University Stuttgert

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ABSTRACT

This paper deals with a multi-server queuing system with constant holding time and an infinite number of waiting places. The offered traffic is Poissonian and is subdivided into R nonpreemptive priority classes. In a queuing system besides the priority classes. In a queuing system besides the probability of waiting, the mean waiting times are of main interest. In this paper now a formula is derived for the mean waiting times two of each priority class r. With this formula the mean waiting times two in a system with priority classes can be calculated by the aid of waiting times two obtained from multi-server systems without priorities.

without priorities.
Numerical results are compared with values of an event by event simulation, which was performed

on a digital computer.

For the calculation of the mean waiting times twr in a queuing system with priorities and an arbitrary holding time distribution the same method can be applied as it is shown for constant holding time in this paper.

1. INTRODUCTION

For the following types of queuing systems with priorities there exist formulae for the mean waiting times :

- Single-server system (n=1) and arbitrary hold-ing time distribution from COBHAM /4/.

- Multi-server system (n>1) and negative exponential holding time distribution from COBHAM et al. (see e.g. /3/, /4/).

The formula for a multi-server avstem and constant holding time derived in this paper completes the above mentioned list. The manner of solution is the following: First of all, the mean waiting time in a queuing system without priorities is regarded. Then a single-server system with priorities is considered. With the aid of a theorem, which was proved for single-server systems in /1/, the mean waiting time of each priority class in single-server sys-

tems can be calculated. After this it is shown that the above mentioned theorem can be extended also to multi-server systems. Hence the mean waiting times of the priority classes in multi--server systems are calculated analogously to those of single server systems.

2. THE SYSTEM

2.1 Description of the system

The properties of the system and the offered traffic are as follows:

- a) n fully accessible servers (n arbitrarily)
 b) infinite number of waiting places
 c) the offered traffic is Poissonian with infinite number of sources and has the
- calling rate λ d) the offered traffic is subdivided into R nonpreemptive priority classes, where r=1 nonpreemptive priority classes, where refise the highest priority class and refise the lowest priority class (Rarbitrarily). The calls of the highest priority class are named 1-calls, the calls of the second priority class are named 2-calls and so on.

 e) the waiting calls of each priority class are served with discipline first-come, first-served and they do not leave the system without first being served.

tem without first being served f) the holding time T is constant and the

same for all priority classes

g) the system is in the statistical equilibrium

2.2 Abbreviations

number of servers

constant holding time

calling rate

A z) • T offered traffic

≅A/n

R number of priority classes

priority class r (r=1,2,...,R) offered traffic of priority class r

P(>t) waiting time distribution of all calls (probability that the waiting time of a

call is greater t)
P(>0) probability of waiting
W(>t) = P(>t)/P(>0) waiting time distribution

tw

= P(>t)/P(>0) waiting time distribute
of the waiting calls
mean waiting time of all calls
= tw/P(>0) mean waiting time of the
waiting calls
mean waiting time of all r-calls
= tw/P(>0) mean waiting time of the
waiting r-calls twr

3. THE QUEUING SYSTEM WITHOUT PRIORITIES

First of all it is useful to consider a queuing system with the properties described in chapter 2.1, but without priority classes. For such a system CROMMELIN has derived formulae for the probability of waiting P(>0), the mean waiting time t_W , and the waiting time distribution W(>t)121.

His manner of solution is briefly described in

the following:

First, he considered time intervals of the length T and set up the equilibrium equations of the state probabilities P(j) (j=0,1,....). To solve this system of equations, Crommelin made use of the generating function which is defined by

$$\psi(z) = \sum_{j=0}^{\infty} z^{j} \cdot P(j)$$

Some transformations led to an expression for $\psi(z)$, in which the denominator is of the form

$$1 - z^n \cdot e^{A(1-z)} \tag{1}$$

For further calculations it was necessary to find the zeros of (1). So the roots β_{ν} of the following equation must be determined:

$$\beta^{n} \cdot e^{-A(\beta-1)} = 1$$
or
$$\beta \cdot e^{-\alpha\beta} = e^{-\alpha} \cdot \sqrt[n]{1} \quad (\text{with } \alpha = A/n) \quad (2)$$

Crommelin showed that this equation for \$ has exactly n roots β_0 , β_1 ,..., β_{n-1} such that $|\beta_0| \le 1$. It can be shown easily that $\beta_0=1$ is always a root of equation (2). The other roots $\beta_1, \dots, \beta_{n-1}$ must be determined by an iterative method.

With these roots of equation (2) and some further calculations Crommelin derived the following formulae for the probability of waiting P(>0) and the mean waiting time:

$$P(>0) = 1 - \frac{n - A}{n-1}$$

$$\prod_{v=1}^{n} (1-\beta_v)$$

$$\mathbf{t}_{\mathbf{W}}^{*} = \frac{T}{A} \begin{bmatrix} n-1 & 1 \\ \sum_{\nu=1}^{n-1} \frac{1}{1-\beta_{\nu}} + \frac{A^{2}-n^{2}+n}{2(n-A)} \end{bmatrix}$$
(4)

$$t_{w} = \frac{t_{w}^{*}}{P(>0)} \tag{5}$$

The most simple multi-server system is a system with n=2 servers. The probability of waiting P(>0) and the mean waiting time t_w^* for this particular system are given by the following formulae:

$$P(>0) = 1 - \frac{2-A}{1-\beta_1}$$

$$t_W^* = \frac{T}{A} \left[\frac{1}{1-\beta_1} + \frac{A^2-2}{2(2-A)} \right]$$

 β_1 is a negative real value and the relation between β_1 and $\alpha=A/n$ is shown in the diagram 1.

4. THE QUEUING SYSTEM WITH PRIORITIES

In this system the offered traffic A is sub-divided into R priority classes. Each priority class has the offered traffic Ar so that

$$\begin{array}{c}
R \\
\sum_{r=1}^{\infty} A_r = A
\end{array}$$

The service discipline is the following:
First, the waiting calls of the priority class
r=1 (1-calls) are served. If there are no more
waiting 1-calls, then the waiting 2-calls are
served and so on. Within each priority class the
calls are served with discipline first-come,
first-served. The service of any call can not be
interrupted by arriving calls of a higher priority class. ity class.

4.1 The single-server system (n=1)

For the special case of n=1 (single-server system) the following theorem was proved /1/:

Theorem: The waiting time distribution function W₁(>t) of the waiting 1-calls (highest priority) is identical with that distribution function, which is obtained, if only the traffic A₁ of the highest priority class is offered to the system.

For the mean waiting time $t_{\rm W}$ of the waiting calls the following formula holds generally:

$$t_{W} = \int_{0}^{\infty} t \cdot w(t) dt = \int_{0}^{\infty} W(>t) dt, \quad (6)$$

where
$$w(t) = -\frac{dW(>t)}{dt}$$

From (6) and the above theorem follows that the mean waiting time t_{w1} of the waiting 1-calls is independent of the calls of the other priority classes. Thus, the mean waiting time t_{w1} can be calculated as in a single-server system without priorities.

To calculate the mean waiting times of the other priority classes, the calls of the priority classes ≤r, or <r respectively, are regarded as one group. The mean waiting time of the calls of one group. The mean waiting time of the calls of such a group is independent of their service discipline. Furthermore, with (6) and the theorem follows that the mean waiting time $t_W(\leq r)$, or $t_W(< r)$ respectively, of this group is independent of the calls with lower priorities. So the mean waiting time $t_W(\leq r)$, or $t_W(< r)$ respectively, can be calculated each in the same manner as t_{W1} .

Therefore, the mean waiting time $t_{W\Gamma}$ of the waiting r-calls can be derived from the following equation:

$$\frac{A(\langle \mathbf{r})}{A(\langle \mathbf{r})} \cdot \mathbf{t}_{\mathbf{W}}(\langle \mathbf{r}) + \frac{A_{\mathbf{r}}}{A(\langle \mathbf{r})} \cdot \mathbf{t}_{\mathbf{W}} = \mathbf{t}_{\mathbf{W}}(\langle \mathbf{r})$$
(7)

with
$$A(, $A(\le r) = \sum_{i=1}^{r} A_i$$$

Equation (7) holds true because the ratio $A(<\mathbf{r})/A(\leq \mathbf{r})$ of the waiting calls with priority classes $\leq \mathbf{r}$ has the mean waiting time $\mathbf{t}_{\mathbf{w}}(<\mathbf{r})$ and the ratio $A_{\mathbf{r}}/A(\leq \mathbf{r})$ has the mean waiting time $\mathbf{t}_{\mathbf{wr}}$. From (7) twr can be obtained easily as

$$t_{WY} = \frac{A(\leq r) \cdot t_{W}(\leq r) - A(< r) \cdot t_{W}(< r)}{A_{p}}$$
 (8)

 $t_w(\leq r)$ and $t_w(< r)$ can be determined as in a single-server system without priorities.

4.2 The multi-server system (n>1)

Section 4.1 dealt with a single-server system. To calculate now the mean waiting times $t_{\rm WF}$ in a system with n>1 it is shown in the following that the theorem of chapter 4.1 is also valid for a multi-server system:

Two separate systems (I and II) are regarded, each with n servers. To each system a traffic A_1 be offered. But to one system (II) an additional traffic A_2 be offered.

System I: Only the traffic A₁ is offered. There are no priority classes. The calls arrive with the time independent calling rate λ_1 . If all servers are busy, there exists a blocking interval. During such a blocking interval an arriving call is set in a waiting place. The probability that the new call is set in the waiting place j shall be $W_{\rm I}({\rm j})$. Then it is

$$P(>0)|_{A_1} = \sum_{j=1}^{\infty} W_{I}(j)$$

where $P(>0)|_{A_1}$ is the probability of waiting if only the traffic A_1 is offered to the system. The conditional waiting time distribution of that call, which was set in the waiting place j_1 shall be W(>t|j). Because the waiting calls are always served with discipline first-come, first-served, W(>t|j) is independent of A_1 and $W_I(j)$. Then, the waiting time distribution function P(>t) of all calls is

$$P(>t) = \sum_{j=1}^{\infty} W(>t|j) \cdot W_{I}(j)$$

The waiting time distribution function W(>t) of the waiting calls is then obtained by division with $P(>0)|_{A_1}$:

$$W(>t) = \frac{1}{P(>0)|_{A_1}} \cdot \sum_{j=1}^{\infty} W(>t|j) \cdot W_{\underline{I}}(j)$$
 (9)

System II: There are two priority classes. The offered traffic A_1 has the priority r=1 and the additional offered traffic A_2 has the priority r=2. In this system the calls are arriving with the time independent calling rate λ_1 or λ_2 respectively. A blocking interval arises if all servers are occupied by 1-calls or 2-calls in an arbitrary mixture. During this blocking interval a 1-queue, consisting of one or more 1-calls, may be built up and may be served step by step. This "birth" and "death" of the considered 1-queue is independent of already waiting or later arriving 2-calls, which are served always after the waiting 1-calls. Hence, the time dependent behaviour of the considered 1-queue is only a function of the Poisson input process with the calling rate λ_1 and of the termination process of no occupied servers. Because the termination process of the 2-calls and the 1-calls is exactly the same, the existing 1-queue is in no respect influenced by the 2-calls. So the time dependent behaviour of a 1-queue in system II is exactly the same one as in system I. Only the average number of 1-queues, built up per unit of time, depends linearly on the global probability of blocking $P(>0)|_{A} = f(A_1 + A_2, n)$. Thus, the number of 1-queues in system II is increased as against the corresponding number of 1-queues in system I by a factor

$$F = \frac{P(>0)|_{A}}{P(>0)|_{A_1}}$$

with $A = A_1 + A_2$

In system II therefore, the probability $W_{II}(j)$ that an arriving 1-call is set in the waiting place j gets

$$W_{II}(j) = F \cdot W_{T}(j)$$

Owing to the service discipline of the waiting calls the conditional waiting time distribution function $W(>t\mid j)$ of a 1-call in the waiting place j is independent of A and $W_{\rm II}(j)$. Then, the waiting time distribution function $P_1(>t)$ of all 1-calls is :

$$P_{1}(>t) = \sum_{j=1}^{\infty} W(>t|j) \cdot W_{II}(j) = F \cdot \sum_{j=1}^{\infty} W(>t|j) \cdot W_{I}(j)$$

$$P_{1}(>t) = \frac{P(>0)|_{A}}{P(>0)|_{A_{1}}} \cdot \int_{j=1}^{\infty} W(>t|j) \cdot W_{I}(j)$$

The waiting time distribution function $W_4(>t)$ of the waiting 1-calls is then obtained by division with the probability of waiting P(>0)

$$W_{1}(>t) = \frac{1}{P(>0)|_{A_{1}}} \cdot \sum_{j=1}^{\infty} W(>t|j) \cdot W_{I}(j)$$
 (10)

Equations (9) and (10) are identical and so the theorem of chapter 4.1 can be also applied on a multi-server system.

It should be noted that this theorem is valid for an arbitrary holding time distribution, provided that the holding time distribution of each priority class is the same!

By applying the theorem of chapter 4.1 in connection with equation (6) on a multi-server system, the mean waiting time t_{w1} of the waiting 1-calls can be calculated with equations (4) and (5):

$$t_{w1} = \frac{T}{A_1 \cdot P(>0)|_{A_1}} \left(\sum_{\nu=1}^{n-1} \frac{1}{1-\beta_{\nu}} + \frac{A_1^2 - n^2 + n}{2(n-A_1)} \right) \quad (11)$$

with
$$P(>0)|_{A_1} = 1 - \frac{n - A_1}{n-1}$$

For the mean waiting times two of the lower priority classes then equation (8) is also available for a multi-server system. With equations (4), (5) and (8) the following formula for two is obtained:

$$t_{Wr} = \frac{T}{A_r} \left[\frac{1}{P(>0)|_{A(\leq r)}} {\binom{n-1}{\sqrt{-1}}} \frac{1}{1-B_{v1}} + \frac{{(\sum_{v=1}^{r} A_v)^2 - n^2 + n}}{2(n-\sum_{v=1}^{r} A_v)} \right] - \frac{1}{P(>0)|_{A(< r)}} {\binom{n-1}{\sqrt{-1}}} \frac{1}{1-B_{v2}} + \frac{{(\sum_{v=1}^{r-1} A_v)^2 - n^2 + n}}{2(n-\sum_{v=1}^{r-1} A_v)} \right]$$
(12)

In this expression $\beta_{V,1}$ are the roots of equation (2) if A is replaced there by A(\$\left(r)\$ and \$\beta_{V,2}\$ are the roots of the same equation if A is replaced there by A(\$\left(r)\$).

The probabilities of waiting $P(>0)|_{A(\le r)}$ and $P(<0)|_{A(< r)}$ are determined with equation (3) as

$$P(>0)|_{A(\leq r)} = 1 - \frac{\sum_{v=1}^{r} A_v}{\prod_{v=1}^{r} (1-\beta_{v1})}$$

and

$$P(>0)|_{A(<\underline{\Gamma})} = 1 - \frac{\sum_{\nu=1}^{r-1} A_{\nu}}{\prod_{\nu=1}^{r-1} (1-\beta_{\nu2})}$$

The mean waiting time of all r-calls is then $t_{W\Gamma}^{\bullet} = \left. P(>0) \right|_{\hat{A}} \circ t_{W\Gamma}^{\bullet} \ .$

Some results obtained from equation (12) are shown in the diagrams 2-9 and are compared with the corresponding results of an event by event simulation. The values of the simulation are determined with a 95%-confidence interval. As it can be seen from the diagrams, the calculated values for the mean waiting times two are situated very well within the 95%-confidence intervals of the simulation.

Ittention should be paid to the following problem: In the case of many servers (e.g. n>5) and a small offered traffic A_1 (e.g. $A_1<0.5$) the determination of the roots β_V (contained in (11)) must be done with high accuracy because in this case a small inaccuracy of β_V causes a remarkable inaccuracy of t_{V1} (see the small values of A_1 in the diagrams 7-9). From equation (8) it can be seen easily that the mean waiting times of all other priority classes are influenced by this inaccuracy of t_{V1} .

5. CONCLUSION

In this paper the mean waiting times of a queuing system with constant holding time and priorities are studied. A formula for the mean waiting time two of each priority class is derived. With this formula the mean waiting times t_{WT} can be determined with waiting times, which are known from queuing systems without priorities. The calculated values are situated very well within the 95%-confidence intervals of values, which are found by simulation.

In the case of many servers (e.g. n>5) and a small offered traffic A₁ (e.g. A₁<0.5) of the highest priority class the accuracy of the calculated values t_{WT} depends strongly on the accuracy of the iterative determination of the roots β_{V} .

Finally it should be noted that the theorem of chapter 4.1 is valid in systems with arbitrary holding time distribution, provided that the holding time distribution of each priority class is the same. If this condition is satisfied, then equation (8) holds true also for the mean waiting times two in a system with arbitrary holding time. Thus, the values of two in a system with arbitrary holding time can be obtained by the same method as it is shown for constant holding time in this paper.

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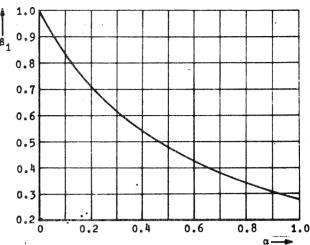


Diagram 1 $\beta_4 = f(\alpha)$ with $\alpha = A/n$ for a queuing system with n = 2

Some examples for the mean waiting times twr:

In each of the following diagrams it is

simulation value (95%-confidence interval)

of calculated value (from formula (12))

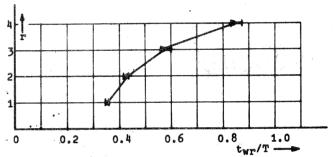


Diagram 2 n = 2, r = 4, A = 1.0 $A_1 = A_2 = A_3 = A_4 = 0.25A$

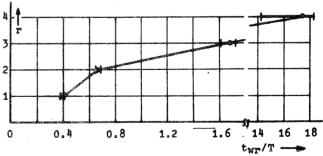


Diagram 3 n = 2, r = 4, A = 1.9 $A_1 = A_2 = A_3 = A_4 = 0.25A$

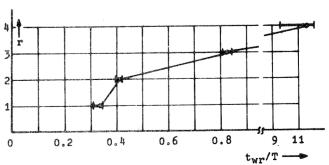
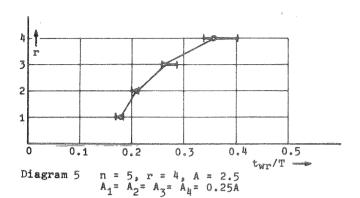


Diagram 4 n = 2, r = 4, A = 1.9 $A_1 = 0.03A, A_2 = 0.25A$ $A_3 = 0.32A, A_4 = 0.4A$



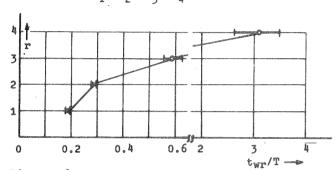
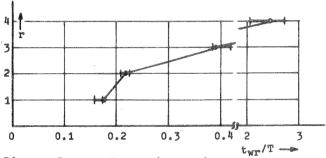
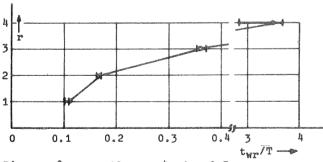


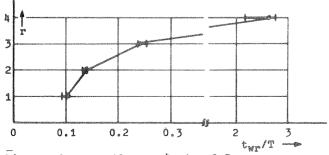
Diagram 6 n = 5, r = 4, A = 4.5 $A_1 = A_2 = A_3 = A_4 = 0.25A$



n = 5, r = 4, A = 4.5 A₁= 0.1A, A₂= 0.25A A₃= 0.3A, A₄= 0.35A Diagram 7



n = 10, r = 4, A = 9.5 $A_1 = A_2 = A_3 = A_4 = 0.25A$ Diagram 8



n = 10, r = 4, A = 9.5 A₁= 0.17A, A₂= 0.21A A₃= 0.27A, A₄= 0.35A Diagram 9

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317/5